ALTERNATING-TIME TEMPORAL EPISTEMIC LOGIC

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Overview

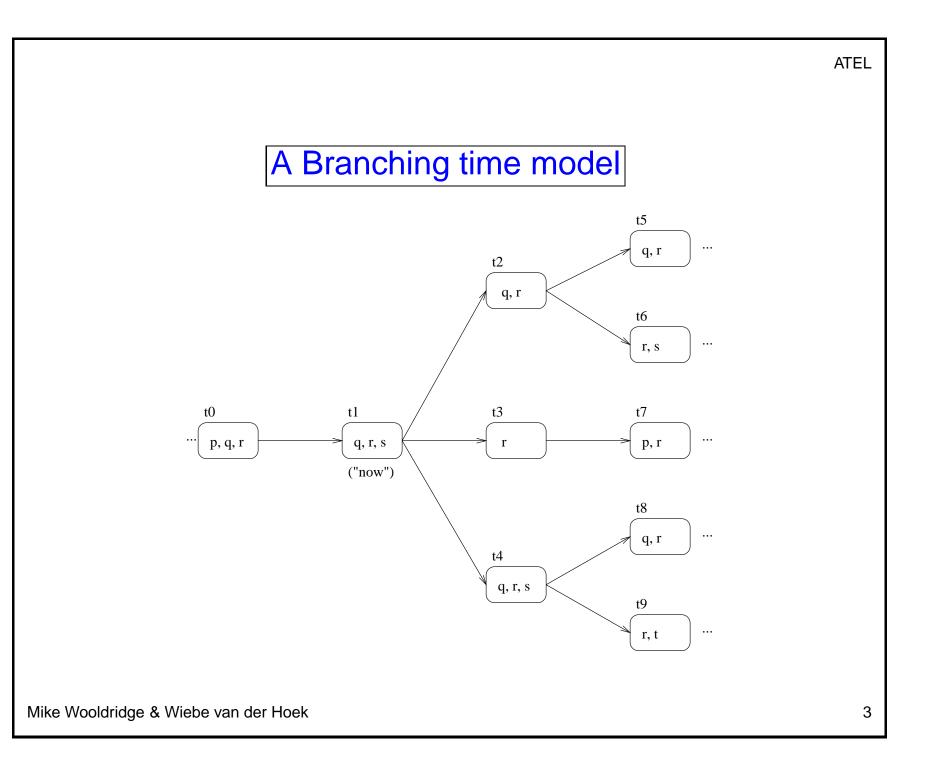
Aims of this presentation:

- review the motivation & history of branching temporal logic in CS;
- introduce the variant of branching temporal logic known as ATL;
- show how ATL can naturally be extended by knowledge modalities in ATEL;
- survey steps towards model checking for ATEL;
- illustrate these ideas with a case study.



Branching Temporal Logic

- Natural to view the possible computations of a system as a tree linear in the past, branching into the future.
- Branching corresponds to different ways in which non-determinism can be resolved.



Computation Tree Logic: CTL

- The most successful branching temporal logic is CTL.
- Extends propositional logic with
 - path quantifiers A, E
 - tense modalities \bigcirc , \diamond , \Box , \mathcal{U}
- Possible combinations of these are restricted as follows:

 $\begin{array}{lll} \mathsf{A} \bigcirc \varphi & \text{``on all paths, } \varphi \text{ is true next} \\ \mathsf{A} \diamondsuit \varphi & \text{``on all paths, } \varphi \text{ is eventually true} \\ \mathsf{A} \bigsqcup \varphi & \text{``on all paths, } \varphi \text{ is always true} \\ \mathsf{A} \varphi \mathcal{U} \psi & \text{``on all paths, } \varphi \text{ is true until } \psi \\ \mathsf{E} \bigcirc \varphi & \text{``on some path, } \varphi \text{ is true next} \\ \mathsf{E} \diamondsuit \varphi & \text{``on some path, } \varphi \text{ is eventually true} \\ \mathsf{E} \bigsqcup \varphi & \text{``on some path, } \varphi \text{ is always true} \\ \mathsf{E} \bigsqcup \varphi & \text{``on some path, } \varphi \text{ is always true} \\ \mathsf{E} \varphi \mathcal{U} \psi & \text{``on some path, } \varphi \text{ is true until } \psi \end{array}$

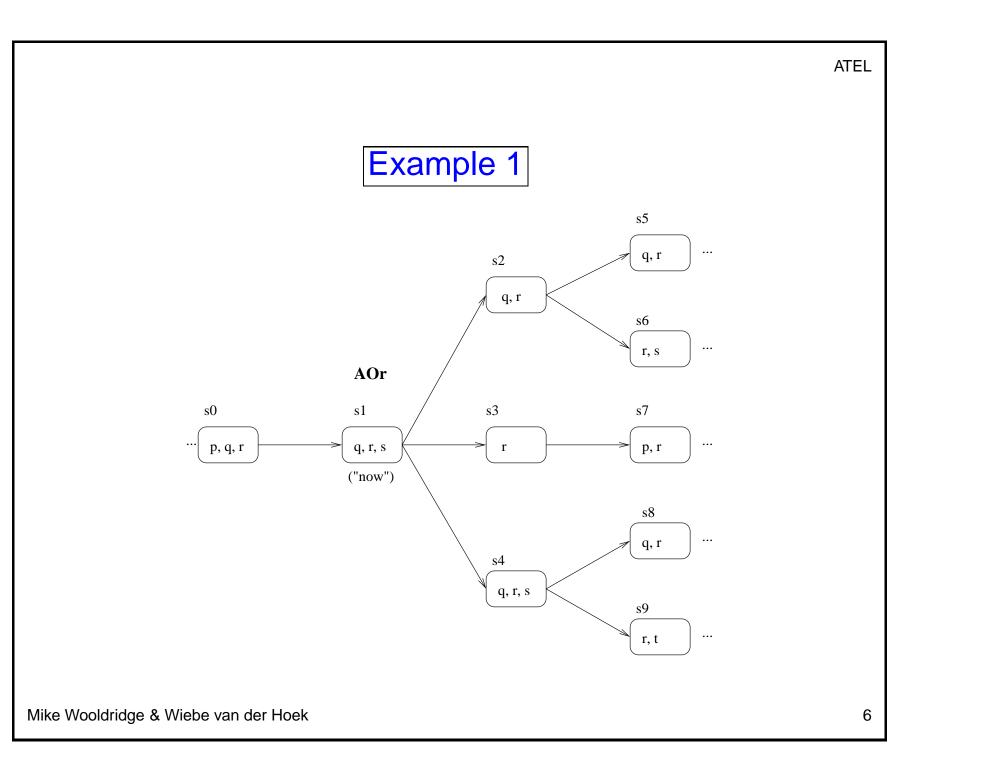
Models for CTL

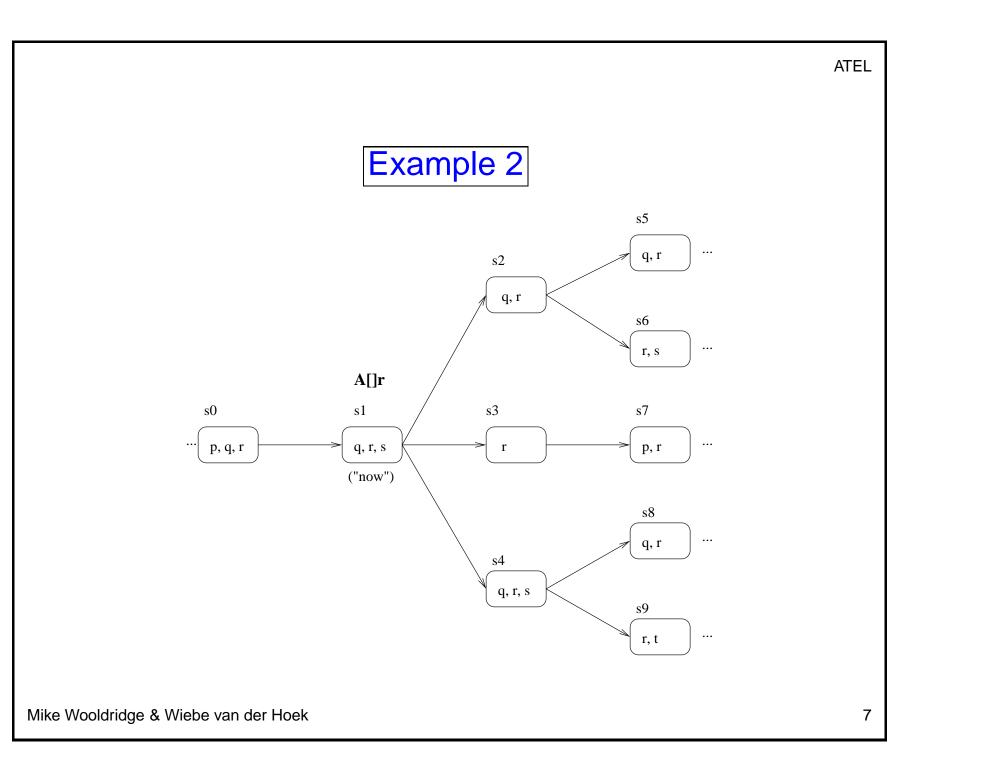
• Models for CTL are *Kripke structures*:

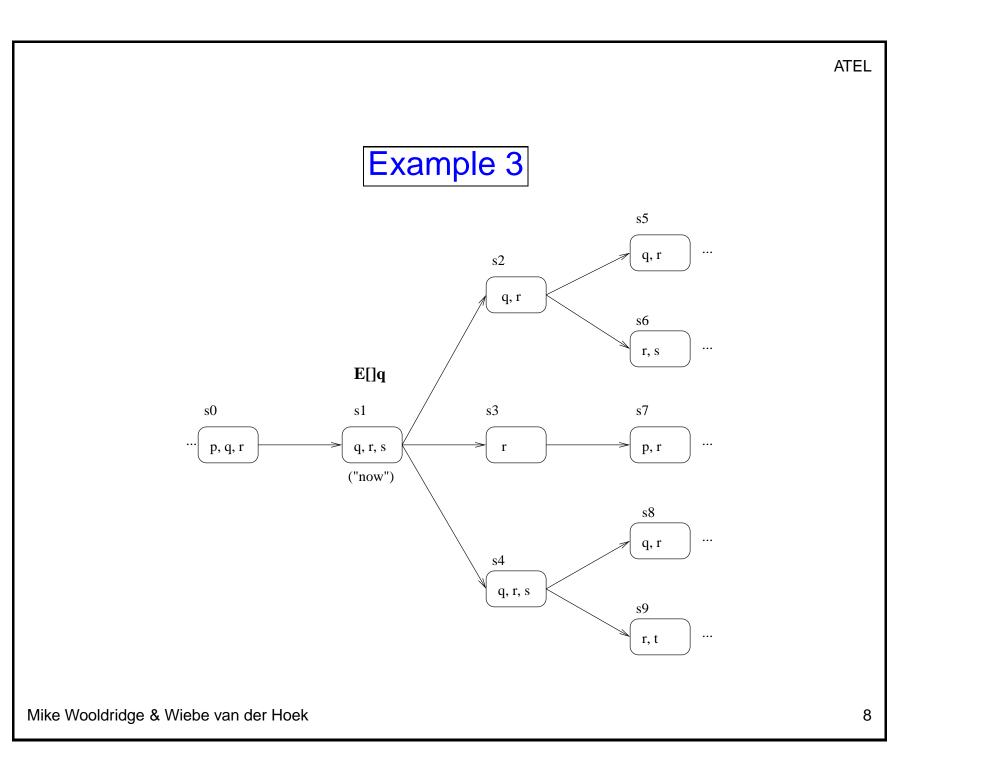
 $\langle S, R, \pi \rangle$

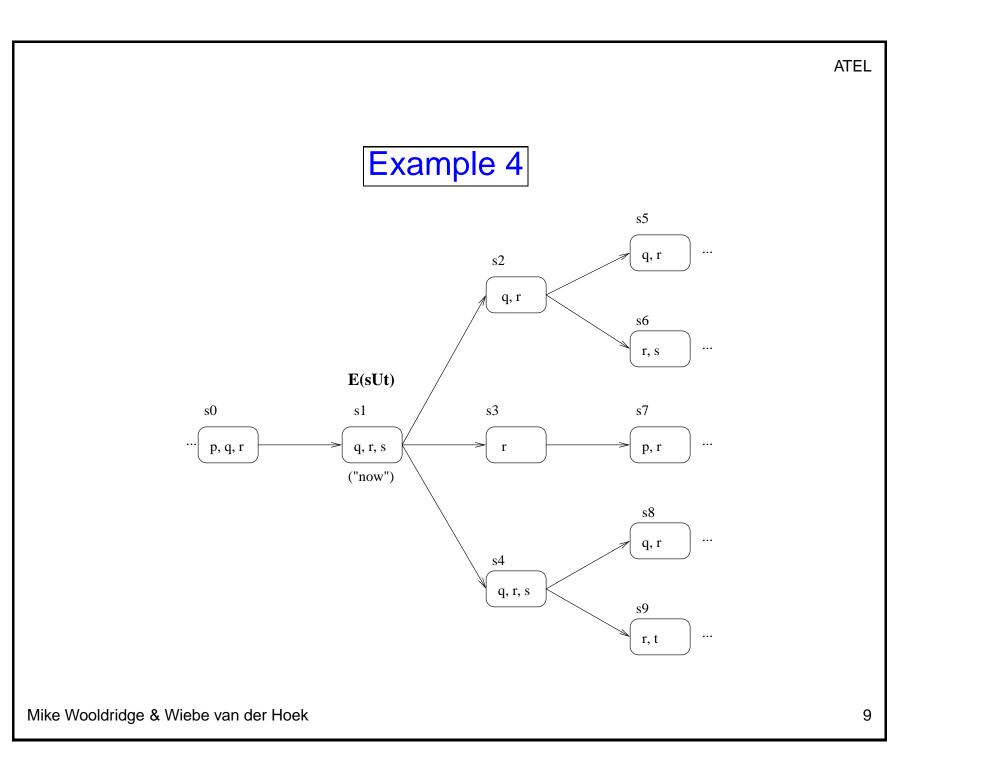
where

- -S is the set of possible system states
- $-R \subseteq S \times S$ is a total binary *next state* relation on *S*
- $-\pi: S \to 2^{\Pi}$ says which propositions are true in each state.
- The branches are obtained by *unwinding* this relation, giving *paths* through the structure.









Computational Properties of CTL

• Proof problem for CTL:

Given CTL formulae φ, ψ can we prove ψ from φ ?

Time complexity: EXPTIME-complete.

(So directly proving properties of systems using CTL looks to be v hard.)

• Model checking problem for CTL:

Given model $M = \langle S, R, \pi \rangle$, state $s_0 \in S$, and formula φ , is φ is true at state s_0 in M?

Time complexity: $O(|M|.|\varphi|)$.

(So model checking properties of systems using CTL is (comparatively) easy... many practical model checkers for CTL available: SMV the best known.



- In 1997, Alur, Henzinger & Kupferman proposed a natural variation of CTL known as *Alternating-time Temporal Logic* (ATL).
- Branching used to model evolution of a system controlled by a set of *agents*, which can affect the future by making *choices*.
- The particular future that will emerge depends on *combination* of choices that agents make.

ATEL **Cooperation Modalities** • Path quantifiers A, E are replaced by cooperation modalities: $\langle\!\langle G \rangle\!\rangle \varphi$ means "group G can cooperate to ensure that φ " or "G have a collective strategy to force φ " • Note that: $\langle\!\langle \emptyset \rangle\!\rangle$ is same as A $\langle\!\langle \Sigma \rangle\!\rangle$ is same as E

Example ATL Formulae

• (mjw>>bored-audience

mjw has a strategy for ensuring that the audience is eventually bored

• $\neg \langle\!\langle mjw \rangle\!\rangle \square excited$

mjw has no strategy for ensuring that the audience is always excited

• $\langle\!\langle gwb, tb \rangle\!\rangle$ \diamond peace

gwb and tb have a strategy for ensuring that, eventually, there is peace (!)

Semantics: Alternating Transition Systems

Semantics of ATL given in terms of ATSs:

 $\langle \Pi, \Sigma, Q, \pi, \delta \rangle,$

where:

- Π is a finite, non-empty set of *atomic propositions*;
- $\Sigma = \{a_1, \ldots, a_n\}$ is a finite, non-empty set of *agents*;
- Q is a finite, non-empty set of states;
- $\pi: Q \to 2^{\Pi}$ gives the set of primitive propositions satisfied in each state;
- $\delta: Q \times \Sigma \to 2^{2^Q}$ is the system transition function: $\delta(q, a)$ is the set of choices available to agent *a* when the system is in state *q*.

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ATL Complexity Properties

• Proof problem for ATL:

Time complexity: EXPTIME-hard (probably much worse).

• ATL model checking:

Time complexity: PTIME-complete.

ATL model checking implemented in MOCHA system

Alternating-time Temporal Epistemic Logic

- ATL is a powerful language for expressing properties of multiagent systems.
- ATEL extends it by *knowledge modalities*, of the kind pioneered by Halpern et al:

$K_i \varphi$	means	agent i knows φ
$C_{\Gamma} arphi$		$arphi$ is common knowledge in Γ
$E_{\Gamma} arphi$		everyone in Γ knows $arphi$
$D_{\Gamma} arphi$		there is distributed knowledge of φ in Γ

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Applications of ATEL: Bit transmission

- Consider a system containing a sender S, a receiver R, and an environment env through which messages are sent.
- Under certain fairness conditions we can express the fact that the environment cannot prevent the sender from sending a message until it is received.

 $\llbracket env \rrbracket send_m \mathcal{U} K_R m \tag{1}$

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Applications of ATEL: Cooperative Problem Solving

 Group Γ can guarantee that their implicit knowledge eventually becomes explicit known by everyone:

$$D_{\Gamma}\varphi \to \langle\!\langle \Gamma \rangle\!\rangle \diamond E_{\Gamma}\varphi \tag{2}$$

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Applications of ATEL: Secure Communication

 Agent *i* can send private information to *j*, without revealing the message to another agent *h*:

$$K_a \varphi \wedge \neg K_j \varphi \wedge \neg K_h \varphi \wedge \langle \langle i, j \rangle \rangle (K_a \varphi \wedge K_j \varphi \wedge \neg K_h \varphi)$$
(3)

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Applications of ATEL: Rights to Secure Communication

- Suppose we have three agents, of which agent 1 knows whether p, i.e., $K_1 p \lor K_1 \neg p$, and this is common knowledge.
- 1 can tell the truth only to 2, or to 2 and 3 separately or he can announce p in public:

 $\langle\!\langle 1 \rangle\!\rangle \bigcirc (K_2 p \land \neg K_3 p) \land \langle\!\langle 1 \rangle\!\rangle \bigcirc (K_2 p \land K_3 p \land \neg C_{\{2,3\}} p) \land \langle\!\langle 1 \rangle\!\rangle \bigcirc (C_{\{2,3\}} p)$

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Applications of ATEL: Knowledge Games

• *Epistemic updates* are interpreted in a simple card game, where the aim of the player is to find out a particular deal *d* of cards.

$$d \to \langle\!\langle i \rangle\!\rangle \diamond (K_i d \wedge \bigwedge_{i \neq j} \neg K_j d) \tag{4}$$

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Applications of ATEL: Knowledge Preconditions

 If Bob knows that the combination of the safe is s, then he is able to open it (o), as long as the combination remains unchanged.

$$K_b(c=s) \to \langle\!\langle b \rangle\!\rangle (\langle\!\langle b \rangle\!\rangle \bigcirc o) \mathcal{U} (c \neq s) \tag{5}$$

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Alternating Epistemic Transition Systems

Semantics in terms of *alternating epistemic transition system* (AETS) is a tuple

$$\langle \Pi, \Sigma, Q, \sim_1, \ldots, \sim_n, \pi, \delta \rangle,$$

where:

- ∏ is a set of *atomic propositions*;
- $\Sigma = \{a_1, \ldots, a_n\}$ is a set of *agents*;
- Q is a set of states;
- $\sim_a \subseteq Q \times Q$ is an *epistemic accessibility relation* for each agent $a \in \Sigma$
- $\pi: Q \to 2^{\Pi}$ is an interpretation
- $\delta: Q \times \Sigma \to 2^{2^Q}$ is the system transition function.

ATEL Complexity Properties

• Proof problem for ATEL:

Time complexity: EXPTIME-hard (probably much worse).

 ATEL model checking: Time complexity: as ATL (PTIME complete) No model checker implemented yet.

An Interpeted Systems Model of Knowledge

- We reduce ATEL model checking to ATL model checking... but to do this, we need to obtain the \sim_a relations!
- Given state *q* ∈ *Q* and agent *a* ∈ Σ, write *state_a(q)* to denote *local* state of agent *a* when the system is in state *q*.
- Then obtain the knowledge accessibility relation as follows:

$$q \sim_a q'$$
 iff $state_a(q) = state_a(q')$. (6)

Model Checking Epistemic Properties with MOCHA

• Suppose we want to check whether, when the system is in some state q, agent a knows φ .

This amounts to showing that

$$\forall q' \in Q \text{ s.t. } state_a(q) = state_a(q') \text{ we have } S, q' \models \varphi.$$
 (7)

• We can represent such properties directly as formulae of ATL, which can be automatically checked using MOCHA...

ATEL

• We want to check whether

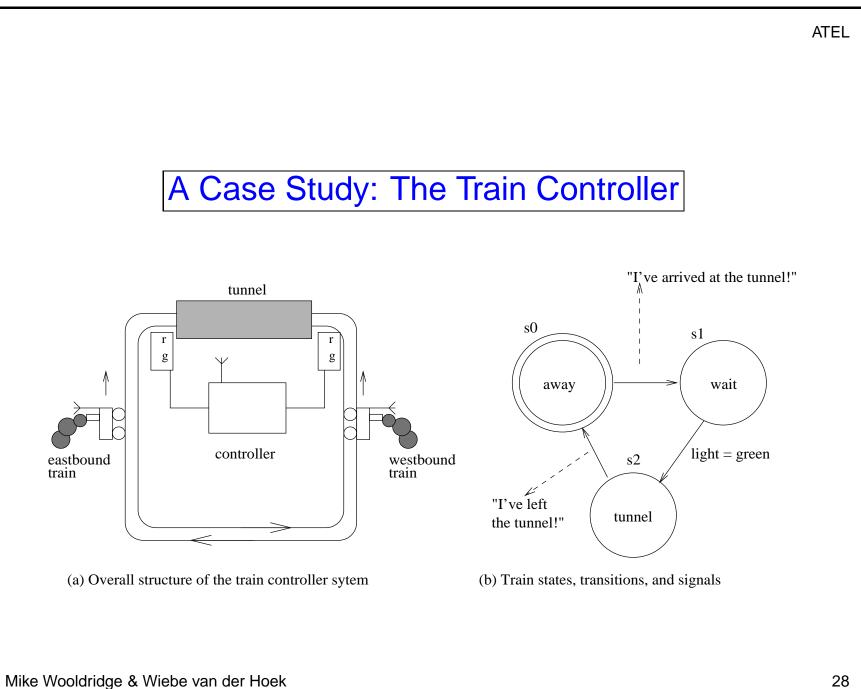
$$S,q \models K_a \varphi$$

• Let $state_a(q) = s$.

• Then we merely need to check:

$$\langle\!\langle \rangle\!\rangle \square ((state_a = s) \to \varphi) \tag{8}$$

- In MOCHA notation:
 - << >>G((stateA = s) -> phi)



A Simple Example

 "When one train is in the tunnel, it knows the other train is not in the tunnel":

$$(state_a = tunnel) \rightarrow K_a(state_b \neq tunnel) \quad (a \neq b \in \{E, W\})$$

• Translating into MOCHA, this schema gives the following:

```
<>>> G ((stateE=tunnel) => (~(stateW=tunnel)))
<<>> G ((stateW=tunnel) => (~(stateE=tunnel)))
```

which were successfully model checked.

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Absence of Knowledge

• When a train is away from the tunnel, it does not know whether or not the other train is in the tunnel.

$$\begin{array}{l} \langle \rangle \rangle \square(state_a \neq tunnel) \rightarrow \\ [(\neg K_a(state_b = tunnel)) \land (\neg K_a(state_b \neq tunnel))] \\ (a \neq b \in \{E, W\}) \end{array}$$

 For the westbound train, we do this by checking the following formulae, both of which fail.

```
<<>> G (~(stateE=tunnel)) => (stateW=tunnel)
<<>> G (~(stateE=tunnel)) => ~(stateW=tunnel)
```

Bringing about Knowledge

• Saying that Γ can bring about knowledge of φ in agent a is the same as saying:

- agent *a*'s state s_1 carries information φ and Γ can ensure that *a* enters s_1 ; or
- agent *a*'s state s_2 carries information φ and Γ can ensure that *a* enters s_2 ; or...
- agent *a*'s state s_n carries information φ and Γ can ensure that *a* enters s_n ; or
- This allows us to rewrite

$$\langle\!\langle \Gamma \rangle\!\rangle \diamond K_a \varphi$$

as:

$$\bigvee_{1 \leq i \leq n} (\langle\!\langle \rangle\!\rangle \square ((state_a = s_i) \to \varphi) \land \langle\!\langle \Gamma \rangle\!\rangle \diamond state_a = s_i)$$

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Conclusions

Branching time: a natural semantics for multiagent systems.

- CTL: a powerful language for representing properties of branching structures... but no notion of *agency* or *cooperation*.
- ATL: a powerful generalisation of CTL for cooperation & agency... but no notion of *knowledge*.
- ATEL: a powerful language for expressing properties of multiagent systems.